

**PRoVisG - Planetary Robotics Vision Ground Processing**

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## D3.5 Sensor Calibration

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**Work package 3 – Interfaces Task 3.5 Sensor Calibration**

**Lead contractor for this deliverable** CTU

**Dissemination level:** Restricted to a group specified by the consortium (including the Commission Services)

### EXECUTIVE SUMMARY

This document provides an explanation of the geometry of the sensors and their models and is aimed to be the reference material of how to use various camera models within the PRoVisG consortium but also for computer vision and photogrammetric communities. It will complement the document D3.2 describing the interfaces to sensors and models. This document also describes related calibration issues where these are useful for the PRoVisG consortium.

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